		[Title]		[Instructor	]
		Advanced Mechatronics	Kazuyoshi Ishida		
[Code]	[Credits]	[Program]	[Semester]	[Language of instruction]	
GTJ501	2	Mechatronics	1st Semester	Tue.∕II	Japanese
Image: Contest of the system of the principle of digital measurement and control system to understand application from the basics about control, mechanism, and signal processing. An aim in this course is to obtain an adequate knowledge of building a system using the various science and technology in mechatronics.         [Objectives]       .         1. To understand the system of mechatronics         2. To understand the mechanisms with articulated links         3. To understand the control elements for robot         [Requirements]         This course will be needed to understand the following fundamental knowledge: classical control, linear differential equation, Laplace transform, transfer function, stability condition of control system, hardware, programming language, and mechanism of operating machine.         [Evaluation]         1. Intermediate examination / 40%         2. Final examination / 40%         3. Quizzes in class / 20%         [Textbooks]         1. 古田勝久 編著, メカトロニクス概論 改訂 3 版, オーム社, ISBN:9784274228841(in Japanese)         2. 橋本 巨, 基礎から学ぶトライボロジー, 森北出版, ISBN: 9784627665910 (in Japanese)					
[Schedule] 1. Introduc	-/深谷健一 tion of mecl	, メカトロニクス入門(第2版), 森北出版, ISBN natronics (machine, electricity, information) of mechatronics	:978462794422	0 (in Japano	ese)
<ol> <li>Link me</li> <li>Kinemati</li> <li>Technolo</li> <li>Technolo</li> <li>Technolo</li> <li>Outline</li> <li>Dynamic</li> <li>Outline</li> <li>Outline</li> <li>Princip</li> <li>Digital</li> <li>Composition</li> <li>Application</li> <li>Application</li> </ol>	chanism an- cics of mecha- gy for mach of the first p cs of mechan of kinematic le of electric circuit and nents of pos- tion to num tion to robo	d articulated robot anism hine element [1] (friction, wear, lubrication) hine element [2] (surface modification, application part & intermediate examination hical systems cs c motor (servomotor, stepping motor) interface itioning system herical controlled machine tool	to Tribology)		

		[Title]		[Instructor]	]	
		Advanced Robotics	Hi	detsugu Ter	ada	
[Code]	[Credits]	[Program]	[Semester] [Hours] [Langua instruct			
GTJ502	2	Mechatronics	1st Semester Thu.∕I Japanese			
taught. Es algorithm a [Objectives] (1) Various (2) Fundam	ure, the ba pecially, a und a funda kinds of ro ental robot	ckground and outlines of robotics and the current structure of an industrial robot, an analytical mental service robot application will be studied. bot structures can be understood. tics control technologies can be understood. cechnologies can be understood.			0.	
[Requirements] The fundamental knowledge of calculus, algebra, kinematics, machine elements design and mechanics of materials are needed. Also, you need English to read the reference papers.						
Reports :40 Presentatio [Textbooks] We will dist	on: 60%	rence papers if necessary.				
ISBN:0471	E. Roshei 026220	m, Robot Evolution -The Development of Auth のための機械工学シリーズ 6 ロボット工学, 朝倉書	-	-		
<ol> <li>Mecha</li> <li>Serial</li> <li>Parall</li> <li>Kinem</li> <li>Mecha</li> <li>Mecha</li> <li>Design</li> <li>Roboti</li> <li>Roboti</li> <li>Roboti</li> <li>Roboti</li> <li>Movin</li> <li>Energ</li> <li>Micro</li> <li>Roboti</li> </ol>	robot el robot natics of Pa- nical elemen of Mechan cs control 1 cs control 2 ics control 3 g robotics ( ies of robot robotics	electric structures of robot rallel robot ents of robotics nical elements (Collision avoidance) (Cooperative control) (Motion planning methods) Gait and wheels) ics ory automations				

		[Title]		[Instructor]		
		Ergonomics	•	amura / Hiro oshiya Kitan	mi Watanabe ura	
[Code]	[Credits]	[Program]	[Semester] [Hours] [Language instructio			
GTJ503	2	Mechatronics	1st Semester Thu.∕IV Japanese			
In ergono	[Outline and purpose] In ergonomics, students learn about the methods, techniques and characteristics of human beings necessary to design systems and artifacts suitable for human beings. The human characteristics are physical					
man/machi	ne interfac	ive and psychological characteristics, and the technice, etc. In addition, students learn how to design improve their communication skills through group in the statement of the	n artifacts b	ased on hu		
[Objectives]						
2. Understa 3. Grasp po	and technol tential req	physical characteristics, psychological characterist logies such as sensors, control, vibration, man-mach uirements of human beings.	nine interface		ics etc.	
4. Discuss a		e prototypes of artifacts based on human-centered d	lesign.			
-		ledge on engineering and liberal arts				
2. Critical r						
[Evaluation	1]					
Assignment Presentatio						
[Textbooks]	·					
Handouts v	vill be distr	ributed if necessary.				
[References						
		roduced during the course.				
[Schedule]						
2. Ethics in	Ergonomi	y and significance of Ergonomics (Okamura) cs (Okamura)				
4. Universa	ıl Design (Ö	gn of artifacts /Notice of the case study theme (Okar Dkamura) esign (1) (Okamura)	mura)			
		sentation (1) (Watanabe)				
	7. Human Centered Design (2) (Okamura)					
	8. Physiological characteristics of human (Okamura)					
	9. Psychological and cognitive characteristics of human (Okamura) 10. Case study and presentation (2) (Watanabe)					
11. Human	11. Human error and accidents (Kitamura)					
		ntify senses (Kitamura)				
	0	logy of condition (Kitamura) rface (Kitamura)				
		esentation (3) (Watanabe)				

		[Title]		[Instructor]		
		Embedded System Design		Suzuki / Shir utomu Tanza	-	
[Code]	[Credits]	[Program]	[Semester] [Hours] [Languag instruction			
GTJ504	2	Mechatronics	1st Semester	Wed./III	Japanese	
[Outline an	d purpose]					
programmin object-orien Recently m	ng is one ted softwa an-machin	r enhancement for electronic machine products of the key technology for software productivi re development approach. e interface has a key role of electronic machine p n processing which are required for structuring ma	ty enhancem roducts. This	ent. This c course also	course covers	
[Objectives]						
<ol> <li>To under</li> <li>To under</li> <li>To under</li> <li>To under</li> <li>To under</li> </ol>	stand object stand struct stand softw stand imag	t-oriented programming etured programming vare development approach re and speech information processing				
[Requireme						
[Evaluation		he C language				
Midterm ex						
Term-end e Report: 40%						
[Textbooks]						
None						
[References	]					
None						
[Schedule]						
1. Orientati	on, softwa	re engineering				
		ent approach				
3. Structure 4. Speech d						
5. Data com						
6. Object-or						
-		ware development approach (using Python) ware development approach (tools for machine lear	ming)			
		ware development approach (machine learning soft				
	10. Midterm exam and sum up of first part					
	<ol> <li>System design and practice 1 (design methodology)</li> <li>System design and practice 2 (evaluation and countermeasures)</li> </ol>					
13. System	design and	practice 3 (development process)				
		practice 4 (documentation process)				
15. Term-er	ia exam an	a sum up				

		[Title]		[Instructor]				
	Adva	nced Engineering Materials	Takaaki Ish	iii/ Shin-ich Shimiz	iro Hira/ Tsuyoshi zu			
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]			
GTJ505	2	Mechatronics	1st Semester	Mon./ III	Japanese/English			
[Outline and purpose] Ceramics, plastics and metals are introduced and discussed in this lecture. Fabrication methods and electric characteristics are lectured for ceramics. Characteristics and molding methods are lectured for plastics. Engineering plastics and composite plastics are included. Characteristics and processing methods are lectured for metals (aluminum alloy, stainless steel alloy and difficult-to-cut materials). Micro-processing technology is included. Understanding characteristics and processing / micro-processing methods for materials are important to design mechatronics systems.								
[Objectives	]							
Understan Understan	ding relation ding how to	onship between mechanical characteristics and o use materials to its applications. ic characteristics of ceramics and its applicatio		ethods.				
[Requireme								
Fundamen	tal knowle	dge of the materials.						
[Evaluation	n]							
Report : 50 Examinatio Attitude : 3	on:17 %							
[Textbooks]								
None.	<u>.</u>							
[References	3]							
None.								
[Schedule]								
<ol> <li>Piezoele</li> <li>Fabrica</li> <li>Electrici</li> <li>Summa</li> <li>Kinds a</li> <li>Kinds a</li> <li>Molding</li> <li>Enginee</li> <li>Composition</li> <li>Alumin</li> <li>Stainle</li> <li>Titaniu</li> <li>High ca</li> </ol>	tion of cera characteri ry of ceran nd charact g method of ering plastic site plastics nmental pr um alloy an ss steel allo m alloy an urbon mate	trostrictive effects. (Ishii) amics. (Ishii) astics of ceramics. (Ishii) nics. (Ishii) eristics of plastics. (Hira) f plastics. (Hira) acs. (Hira) s. (Hira)	ira) oon steel and o	cast iron).	(Shimizu)			

[Title]				[Instruct	or]		
	Adva	Advanced Actuator Engineering Takaaki Ishii/ Toshiya Kitamura					
[Code]	[Credits]	[Program]	[Semester] [Hours] [Language instructio				
GTJ506	2	Mechatronics	1st Semester	Mon.∕IV	Japanese/English		
[Outline an	nd purpose						
Actuators are widely used in many kinds of mechanical systems. In this lecture, electromagnetic motors (AC / DC motors, servomotors, stepping motors, etc.), fluid actuators (hydraulic actuators, pneumatic actuators, etc.) and solid state actuators (piezoelectric / electrostrictive actuators) are introduced. Fundamental properties (driving principle, characteristics, how to use, etc.) are lectured and discussed. Understanding characteristics and selection / use of the actuators are the purposes.							
[Objectives	]						
-		racteristics of the actuators.					
		on of the actuators. the actuators.					
[Requireme	ents]						
		dge of physics.					
Fundamen	tal knowle	dge of control systems.					
[Evaluation	n]						
Report : 75							
Attitude : 2	25 %						
[Textbooks]	]						
None.							
[References	s]						
None.							
[Schedule]							
	line of the	actuators. (Kitamura)					
-		lectric motors. (Kitamura)					
	-	(Kitamura)					
4. DC serv		(Kitamura) (Kitamura)					
		s. (Kitamura)					
		fluid actuators. (Kitamura)					
	8. Fundamentals of the hydraulic actuators. (Kitamura)						
	9. Fundamentals of the pneumatic actuators. (Kitamura) 10. Applications on fluid actuators. (Kitamura)						
11. Fundan	11. Fundamentals of the solid state actuators. (Ishii)						
		cteristics of the solid state actuators. (Ishii) istics of the solid state actuators. (Ishii)					
		istics of the solid state actuators. (Ishii) solid state actuators. (Ishii)					
		lid state actuators. (Ishii)					

		[Title]		[Instructor	]	
	Advanced	Electromagnetic Wave Engineering		Lianhua Jin		
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]	
GTJ507	2	Mechatronics	2nd Semester	Mon./II	Japanese	
[Outline a	nd purpose]					
The Electr	omagnetic V	Wave is the most important science and teo required for any advance researchers in the l		dern commu	inication. The	
[Objectives	2]					
-		eory of the wave equation in Electromagnetic	c Wave and its techn	ical applicat	tion	
[Requirem	ontal					
-		the Electromagnetism				
Dasie kilov	fleuge about	the Incentinagnetism				
[Evaluatio	n]					
Fundamen	tal knowled	ge and understanding about the Electromag	netic Wave			
[m .1 1	1					
[Textbooks						
[Reference	s]					
[Schedule]						
		rms of the Gauss low and the Ampere low				
	xwell equat xwell equat					
		(1 dimension)				
		(3 dimension)				
	diation					
(7) Re						
		the Electromagnetic Waves				
	terference a					
		the Electromagnetic waves				
	iffraction ap					
		f the Electromagnetic waves				
	olarization a ummary	ipplications				
(10) 0	ummaty					

[Title]			[Instructor]			
	Computer Networks of Embedded Systems Masayuki Mor Tsutomu Tan Hiromitsu Nis		itomu Tanza	wa /		
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]	
GTJ508	2	Mechatronics	1st Semester	Thu. / II	Japanese	

## [Outline and purpose]

The control computer and the communication between the individual devices are essential for the embedded system used in mechatronics products. In recent years, wireless and internet connections have become widespread in addition to traditional communication methods that connect devices with cables.

In this course, students enrolled in this course will learn about computer networks based on communication technology, from different methods used in embedded systems to the Internet. Specifically, we aim to understand the methods of communication between typical personal computers and embedded microcontrollers and with peripheral devices, as well as the TCP/IP protocol used in the Internet system. Students will also be given practical training in networking using switching devices.

## [Objectives]

1  $\,$  Enable to explain the communication interface between the computer and peripheral modules in embedded system

2. Enable to explain the basics of the digital signals and communications

- 3. Enable to build a small computer communication system.
- 4. Enable to explain the working of each layer of OSI Reference Model and its necessity.
- 5. Enable to explain TCP/IP protocol and to read information in packet headers.

6. Enable to explain basic matters on internet such as route control and application protocol such as DNS.

## [Requirements]

Basic knowledge of computer architecture and programming is required as the premise.

[Evaluation]

The comprehension level is evaluated through several reports and mini tests.

## [Textbooks]

[References]

[Schedule]

- 1. Introduction to communication methods
- 2. Communication methods for embedded computers
- 3. Data Communication by wireless
- 4. Typical microcomputer communication RS232C (1)
- 5. Typical microcomputer communication RS232C (2)
- 6. Typical Microcomputer Communication USB(1)
- 7. Typical Microcomputer Communication USB(2)
- 8. Internet protocol, OSI reference model, packet communication, composition of computer networks
- 9. The first layer communication, the second layer communication
- 10. The third layer communication 1 (overview, IP address, subnet)
- 11. The third layer communication 2 (Details of the third layer communication, ARP, router, routing)
- 12. Routing protocols
- 13. The 4th layer communication (TCP, UDP)
- 14. Hands-on Practice of Network Construction (how to operate a routing/switching device)
- 15. Hands-on Practice of Network Construction (configuration for building a network)

		[Title]	[Instructor]				
А	dvanced M	edical and Welfare Devices Engineering	Hidetsug	u Terada / K	oji Makino		
[Code]	[Credits]	[Program]	[Semester] [Hours] [Languaginstruct				
GTJ509	2	Mechatronics	1st Semester	Mon.∕II			
[Outline an	d purpose]						
equipment certification understand process of 1	Medical and welfare equipment must be not only equipment from the viewpoint of engineering but also equipment that fully secures biological safety. Therefore, understanding of laws such as complicated approval / certification / business permission, risk management, electric safety / electromagnetic compatibility, complex understanding of the market are essential. In this lecture, we learn about various matters necessary in the process of newly developing medical and welfare equipment based on the needs of the medical field and the welfare site.						
		the ensuring safety of medical and welfare equipme					
		be planned by themselves and application docu	iments to be	submitted 1	to the Ethics		
committee ( (3) It can u		area. nedical device certification and welfare equipment	authenticatio	n procedure			
[Requireme			antiroritatio	ii procedure			
		owledge of calculus, algebra, kinematics, machin		lesign and	mechanics of		
materials a	re needed.	Also, you need English to read the reference papers	3.				
[Evaluation	ı]						
Reports :50	%						
Test: 50%							
[Textbooks]							
We will dist	tribute refe	rence papers if necessary.					
[References	]						
None							
[Schedule]							
Because the plan of the medical department has not been decided, the detailed schedule is undecided. Considering the medical service in our hospital, the lecture hour for several times will be from 18:00 to 21:00 on Tuesday. The first lecture will be started at April 13th, II period. Please check announcement in CNS.							

[Title]				[Instructor]	
	М	lechatronics Special Lecture I			
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ601	1	Mechatronics	Intensive	/	Japanese
[Outline an					<u></u>
The lecture	indicates t	the state of the art of mechatronics.			
[Objectives					
To acquire electronics		sciplinary knowledge on mechatronics engineering	based on the	knowledge	of mechanics,
cicculonics	ana compa				
[Requireme	ents]				
Basic know	ledge of me	echatronics for undergraduate level.			
[Evaluation	1]				
Presentatio	n 100%				
[Textbooks]					
[References					
Interences	3]				
[Schedule]					

[Title]				[Instructor]	
	Μ	echatronics Special Lecture II			
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ602	1	Mechatronics	Intensive	/	Japanese
[Outline an					
The lecture	indicates t	the state of the art of mechatronics.			
[Objectives]					
To acquire electronics		sciplinary knowledge on mechatronics engineering ter science.	based on the	knowledge	of mechanics,
	ana compa				
[Requireme					
Basic know	ledge of me	echatronics for undergraduate level.			
[Evaluation					
Presentatio	on 100%				
[Textbooks]					
[References	]				
Interences	,				
[					
[Schedule]					

		[Title]		[Instructor]	]
	Semina	ar in Mechatronics Engineering IA	all academic supervisors		
[Code]	[Credits]	[Program]	[Semester] [Hours] [Langua instruction		
GTJ603	1	Mechatronics	1st Semester		English⁄ Japanese
[Outline an	d purpose]				
It is necess the related	ary to revie field. This	ew the related literatures, to consider the theme of program provides information on approaching thos collaboration on research group is also studied thro	e literatures.	Other than	
[Objectives]		condoctation on resourch group is also studied on	ough the senin		
		hrough the knowledge from this seminar.			
	-				
[Requireme					
General kn	owledge of	engineering relating research at undergraduate co	arse.		
[Evaluation	1]				
Integrated	evaluation	: 100%			
[Textbooks]					
[m. c	1				
[References	5]				
[Schedule]					

		[Title]		[Instructor]				
	Semina	ar in Mechatronics Engineering IB	all act	all academic supervisors				
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]			
GTJ604	1	Mechatronics	2nd Semester		English/ Japanese			
[Outline an	d purpose]							
It is necess the related	It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the seminar.							
[Objectives]		<u> </u>						
		hrough the knowledge from this seminar.						
[Requireme	ents]							
		engineering relating research at undergraduate cou	arse.					
[Evaluation	n]							
Integrated	evaluation	: 100%						
[Textbooks]	I							
[References	3]							
[Schedule]								
[Schedule]								

		[Title]		[Instructor	]	
	Semina	r in Mechatronics Engineering IIA	all academic supervisors			
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]	
GTJ605	1	Mechatronics	1st Semester		English/ Japanese	
the related literatures. through the [Objectives]	ary to revie l field in a Other tha e seminar. ]	ew the related literatures, to consider the theme of addition to the Seminar I. This program provid n that, the way of communication and collabora	les informatio	on on appr	oaching those	
[Requiremo General kn		engineering relating research at undergraduate co	urse.			
[Evaluation	n]					
Integrated	evaluation	: 100%				
[Textbooks]						
[References	5]					
[Schedule]						

		[Title]		[Instructor	]	
	Semina	r in Mechatronics Engineering IIB	all academic supervisors			
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]	
GTJ606	1	Mechatronics	2nd Semester		English/ Japanese	
the related literatures. through the [Objectives	ary to revie l field in a Other tha e seminar. ]	ew the related literatures, to consider the theme of addition to the Seminar I. This program provid in that, the way of communication and collabora	les informatio	on on appr	baching those	
[Requireme General kn		engineering relating research at undergraduate co	urse.			
[Evaluation	n]					
Integrated	evaluation	: 100%				
[Textbooks]						
[References	5]					
[Schedule]						

		[Title]		[Instructor	]			
	Research	Work in Mechatronics Engineering IA	all academic supervisors					
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]			
GTJ607	2	Mechatronics	1st Semester		English⁄ Japanese			
[Outline and purpose] It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the research.								
[Objectives] To direct or		hrough the knowledge from this research.						
[Requireme General kn		engineering relating research at undergraduate co	urse.					
[Evaluation Integrated		: 100%						
[Textbooks]								
[References	5]							
[Schedule]								

		[Title]		[Instructor	]			
	Research	Work in Mechatronics Engineering IB	all ac	all academic supervisors				
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]			
GTJ608	2	Mechatronics	2nd Semester		English⁄ Japanese			
[Outline and purpose] It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the research.								
[Objectives] To direct or		hrough the knowledge from this research.						
[Requireme		· · · · · · · · · · · · · · · · · · ·						
General kn	owledge of	engineering relating research at undergraduate cou	urse.					
[Evaluatior	1]							
Integrated	evaluation	: 100%						
[Textbooks]								
[References	ş]							
[Schedule]								

		[Title]		[Instructor	·]
	Research Work in Mechatronics Engineering IIA		all ac	ademic supe	ervisors
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ609	2	Mechatronics	1st Semester		English⁄ Japanese
the related literatures. through the [Objectives	ary to revie l field in a Other tha e research. ]	ew the related literatures, to consider the theme of addition to the Research I. This program provid n that, the way of communication and collaboration prough the knowledge from this research.	les informatio	on on appr	oaching those
[Requireme General kn		engineering relating research at undergraduate co	urse.		
[Evaluation Integrated		· 100%			
Integrateu	evaluation	. 10070			
[Textbooks]					
[References	5]				
[Schedule]					

		[Title]		[Instructor	]
	Research V	Vork in Mechatronics Engineering IIB	all academic supervisors		
[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ610	2	Mechatronics	2nd Semester		English/ Japanese
the related literatures. through the [Objectives	ary to revie l field in a Other tha e research. ]	ew the related literatures, to consider the theme of addition to the Research I. This program provident that, the way of communication and collaboration mrough the knowledge from this research.	les informatio	on on appro	oaching those
[Requireme General kn		engineering relating research at undergraduate co	urse.		
[Evaluation	n]				
Integrated		: 100%			
[Textbooks]					
[Schedule]					