[Title]				[Instructor]		
Advanced Mechatronics				Kazuyoshi Ishida		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ501	2	Mechatronics		1st Semester	Tue.／II	Japanese

[Outline and purpose]

This course involves the principle of digital measurement and control system to understand application from the basics about control, mechanism, and signal processing. An aim in this course is to obtain an adequate knowledge of building a system using the various science and technology in mechatronics.

[Objectives]

1. To understand the system of mechatronics
2. To understand the mechanisms with articulated links
3. To understand the control elements for robot

[Requirements]

This course will be needed to understand the following fundamental knowledge: classical control, linear differential equation, Laplace transform, transfer function, stability condition of control system, hardware, programming language, and mechanism of operating machine.

[Evaluation]

1. Intermediate examination / 40%
2. Final examination / 40%
3. Quizzes in class / 20%

[Textbooks]

1. 神崎一男, 基礎メカトロニクス, 共立出版, ISBN:9784320081048 (in Japanese)
2. 橋本　巨, 基礎から学ぶトライボロジー, 森北出版, ISBN: 9784627665910 (in Japanese)

[References]

1. 土谷武士／深谷健一, メカトロニクス入門（第 2 版）, 森北出版, ISBN:9784627944220 (in Japanese)
2. 応用制御工学, 丸善, ISBN:462104477X (in Japanese)
3. 雨宮好文／高木章二, ディジタル制御入門 改訂 2 版, オーム社, ISBN:4274086704 (in Japanese)

[Schedule]

1. Introduction of mechatronics (machine, electricity, information)
2. Practical examples of mechatronics
3. Link mechanism and articulated robot
4. Kinematics of mechanism
5. Technology for machine element [1] (friction, wear, lubrication)
6. Technology for machine element [2] (surface modification, application to Tribology)
7. Outline of the first part & intermediate examination
8. Dynamics of mechanical systems
9. Outline of kinematics
10. Principle of electric motor (servomotor, stepping motor)
11. Digital circuit and interface
12. Components of positioning system
13. Application to numerical controlled machine tool
14. Application to robot
15. Outline of the last half & final examination

[Title]				[Instructor]		
Advanced Robotics				Hidetsugu Terada		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ502	2	Mechatronics		1st Semester	Thu.／I	Japanese

[Outline and purpose]

At this lecture, the background and outlines of robotics and the current trends of the robot technology will be taught. Especially, a structure of an industrial robot, an analytical solution of a robot motion, a control algorithm and a fundamental service robot application will be studied.

[Objectives]

(1) Various kinds of robot structures can be understood.
(2) Fundamental robotics control technologies can be understood.
(3) The trend of robot technologies can be understood.

[Requirements]

The fundamental knowledge of calculus, algebra, kinematics, machine elements design and mechanics of materials are needed. Also, you need English to read the reference papers.

[Evaluation]

Reports :40%
Presentation: 60%

[Textbooks]

We will distribute reference papers if necessary.

[References]

1.　Mark E. Rosheim, Robot Evolution -The Development of Authrobotics-, John Wiley & Sons, Inc., ISBN:0471026220
2.　則次俊郎ほか, 学生のための機械工学シリーズ 6　ロボット工学, 朝倉書店, ISBN:4254237367 (In Japanese)

[Schedule]

1.　Introductions of the robotics
2.　Mechanical and electric structures of robot
3.　Serial robot
4.　Parallel robot
5.　Kinematics of Parallel robot
6.　Mechanical elements of robotics
7.　Design of Mechanical elements
8.　Robotics control 1 (Collision avoidance)
9.　Robotics control 2 (Cooperative control)
10.　Robotics control 3 (Motion planning methods)
11.　Moving robotics (Gait and wheels)
12.　Energies of robotics
13.　Micro robotics
14.　Robotics and factory automations
15.　Research of foreign trends

[Title]	[Instructor]
Ergonomics	Miyoshi Okamura / Kazuyoshi Ishida / Toshiya Kitamura

[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ503	2	Mechatronics	1st Semester	Thu.／IV	Japanese

[Outline and purpose]

　　In ergonomics, students learn about the methods, techniques and characteristics of human beings necessary to design systems and artifacts suitable for human beings. The human characteristics are physical characteristics, cognitive and psychological characteristics, and the technologies are sensors, control, vibration, man/machine interface, etc. In addition, students learn how to design artifacts based on human-centered design. Students also improve their communication skills through group discussions and exercises.

[Objectives]

1. Understand human physical characteristics, psychological characteristics, cognitive characteristics etc.
2. Understand technologies such as sensors, control, vibration, man-machine interface and others.
3. Grasp potential requirements of human beings.
4. Discuss and propose prototypes of artifacts based on human-centered design.

[Requirements]

1. Fundamental knowledge on engineering and liberal arts
2. Critical mind and curiosity

[Evaluation]

Assignments: 70%
Presentations: 30%

[Textbooks]

Handouts will be distributed if necessary.

[References]

References will be introduced during the course.

[Schedule]

1. Orientation, History and significance of Ergonomics (Okamura)
2. Ethics in Ergonomics (Okamura)
3. Ergonomics in design of artifacts /Notice of case study theme (Okamura)
4. Universal Design (Okamura)
5. Human Centered Design (1) (Okamura)
6. Case study and presentation (1) (Ishida)
7. Human Centered Design (2) (Okamura)
8. Physiological characteristics of human (Okamura)
9. Psychological and cognitive characteristics of human (Okamura)
10. Case study and presentation (2) (Ishida)
11. Human error and accidents (Kitamura)
12. Measuring technology of sensitivity (Kitamura)
13. Measuring technology of condition (Kitamura)
14. Man-machine interface (Kitamura)
15. Case study and presentation (3) (Ishida)

[Title]	[Instructor]
Embedded System Design	Yoshimi Suzuki / Shinji Kotani / Tsutomu Tanzawa

[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ504	2	Mechatronics	1st Semester	Wed.／III	Japanese

[Outline and purpose]

Software productivity enhancement for electronic machine products has much attention. Object-oriented programming is one of the key technology for software productivity enhancement. This course covers object-oriented software development approach.
Recently man-machine interface has a key role of electronic machine products. This course also covers image and speech information processing which are required for structuring man-machine interface.

[Objectives]

1. To understand object-oriented programming
2. To understand structured programming
3. To understand software development approach
4. To understand image and speech information processing

[Requirements]

Programming skill of the C language

[Evaluation]

Midterm exam: 40%
Term-end exam: 40%
Report: 40%

[Textbooks]

None

[References]

None

[Schedule]

1. Orientation, software engineering
2. Software development approach
3. Structured programming
4. Speech data and image data
5. Data compression algorithm
6. Object-oriented programming
7. Object-oriented software development approach (using Python)
8. Object-oriented software development approach (tools for machine learning)
9. Object-oriented software development approach (machine learning software)
10. Midterm exam and sum up of first part
11. System design and practice 1 (design methodology)
12. System design and practice 2 (evaluation and countermeasures)
13. System design and practice 3 (development process)
14. System design and practice 4 (documentation process)
15. Term-end exam and sum up

[Title]				[Instructor]		
Advanced Engineering Materials				Takaaki Ishii/ Shin-ichiro Hira/ Tsuyoshi Shimizu		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ505	2	Mechatronics		1st Semester	Mon./III	Japanese

[Outline and purpose]

Ceramics, plastics and metals are introduced and discussed in this lecture. Fabrication methods and electric characteristics are lectured for ceramics. Characteristics and molding methods are lectured for plastics. Engineering plastics and composite plastics are included. Characteristics and processing methods are lectured for metals (aluminum alloy, stainless steel alloy and difficult-to-cut materials). Micro-processing technology is included. Understanding characteristics and processing / micro-processing methods for materials are important to design mechatronics systems.

[Objectives]

Understanding relationship between mechanical characteristics and processing methods.
Understanding how to use materials to its applications.
Understanding electric characteristics of ceramics and its applications.

[Requirements]

Fundamental knowledge of the materials.

[Evaluation]

Report : 50 %
Examination : 17 %
Attitude : 33 %

[Textbooks]

None.

[References]

None.

[Schedule]

1. Fundamentals of ceramics.　(Ishii)
2. Piezoelectric / electrostrictive effects.　(Ishii)
3. Fabrication of ceramics.　(Ishii)
4. Electric characteristics of ceramics.　(Ishii)
5. Summary of ceramics.　(Ishii)
6. Kinds and characteristics of plastics.　(Hira)
7. Molding method of plastics.　(Hira)
8. Engineering plastics.　(Hira)
9. Composite plastics.　(Hira)
10. Environmental problems and safety of plastics.　Summary.　(Hira)
11. Aluminum alloy and its processing.　(Shimizu)
12. Stainless steel alloy and its processing.　(Shimizu)
13. Titanium alloy and its processing.　(Shimizu)
14. High carbon materials and its processing (carbon steel, high carbon steel and cast iron).　(Shimizu)
15. Summary of the metals.　(Shimizu)

[Title]	[Instructor]
Advanced Actuator Engineering	Takaaki Ishii/ Toshiya Kitamura

[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ506	2	Mechatronics	1st Semester	Mon.／IV	Japanese

[Outline and purpose]

Actuators are widely used in many kinds of mechanical systems.　In this lecture, electromagnetic motors (AC / DC motors, servomotors, stepping motors, etc.), fluid actuators (hydraulic actuators, pneumatic actuators, etc.) and solid state actuators (piezoelectric / electrostrictive actuators) are introduced.　Fundamental properties (driving principle, characteristics, how to use, etc.) are lectured and discussed.　Understanding characteristics and selection / use of the actuators are the purposes.

[Objectives]

1. Understanding characteristics of the actuators.
2. Appropriate selection of the actuators.
3. Appropriate use of the actuators.

[Requirements]

Fundamental knowledge of physics.
Fundamental knowledge of control systems.

[Evaluation]

Report：75 %
Attitude：25 %

[Textbooks]

None.

[References]

None.

[Schedule]

　1. The outline of the actuators.　(Kitamura)
　2. Principles of the electric motors.　(Kitamura)
　3. Stepping motors.　(Kitamura)
　4. DC servomotors.　(Kitamura)
　5. AC servomotors.　(Kitamura)
　6. High power motors.　(Kitamura)
　7. The outline of the fluid actuators.　(Kitamura)
　8. Fundamentals of the hydraulic actuators.　(Kitamura)
　9. Fundamentals of the pneumatic actuators.　(Kitamura)
10. Applications on fluid actuators.　(Kitamura)
11. Fundamentals of the solid state actuators.　(Ishii)
12. Mechanical characteristics of the solid state actuators.　(Ishii)
13. Electric characteristics of the solid state actuators.　(Ishii)
14. Evaluation of the solid state actuators.　(Ishii)
15. Applications on solid state actuators.　(Ishii)

[Title]				[Instructor]		
Advanced Electromagnetic Wave Engineering				Lianhua Jin		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ507	2	Mechatronics		2nd Semester	Mon.／II	Japanese

[Outline and purpose]

The Electromagnetic Wave is the most important science and technology for the modern communication. The basic knowledges are required for any advance researchers in the Mechatronics.

[Objectives]

Understanding the theory of the wave equation in Electromagnetic Wave and its technical application

[Requirements]

Basic knowledge about the Electromagnetism

[Evaluation]

Fundamental knowledge and understanding about the Electromagnetic Wave

[Textbooks]

[References]

[Schedule]

    (1) Differential forms of the Gauss low and the Ampere low
    (2) Maxwell equations 1
    (3) Maxwell equations 2
    (4) Wave equation (1 dimension)
    (5) Wave equation (3 dimension)
    (6) Radiation
    (7) Receiver
    (8) Application of the Electromagnetic Waves
    (9) Interference of the Electromagnetic Waves
    (10) Interference applications
    (11) Diffraction of the Electromagnetic waves
    (12) Diffraction applications
    (13) Polarization of the Electromagnetic waves
    (14) Polarization applications
    (15) Summary

[Title]				[Instructor]		
Computer Networks of Embedded Systems				Masayuki Morisawa / Tsutomu Tanzawa / Hiromitsu Nishizaki		
[Code]	[Credits]	[Code]		[Credits]	[Code]	[Credits]
GTJ508	2	GTJ508		2	GTJ508	2

[Outline and purpose]

　　The computer for control purpose and the communications between each device are vital for the embedded system used in Mechatronics. In recent years wireless and internet connections are becoming widespread on top of traditional communication methods which connect devices with cables.

　In this lecture, we learn extensively about computer network based on communication technology from various methods used in embedded systems to internet. Specifically aiming at understanding methods of communication between typical PCs and embedded microcontrollers and with peripheral equipments, as well as TCP/IP protocol used in internet system.

[Objectives]

1　Enable to explain the communication interface between the computer and peripheral modules in embedded system
2.　Enable to explain the basics of the digital signals and communications
3.　Enable to build a small computer communication system.
4.　Enable to explain the working of each layer of OSI Reference Model and its necessity.
5.　Enable to explain TCP/IP protocol and to read information in packet headers.
6.　Enable to explain basic matters on internet such as route control and application protocol such as DNS.

[Requirements]

Basic knowledge of computer architecture and programming is required as the premise.

[Evaluation]

The comprehension level is evaluated through several reports and mini tests.

[Textbooks]

[References]

[Schedule]
 1. Introduction to the computer network to embedded system
 2. The communication interface in the embedded system
 3. The wireless communication interface
 4. The typical Communication interface1 - RS232C(1)
 5. The typical Communication interface2 - RS232C(2)
 6. The typical Communication interface3 - USB (1)
 7. The typical Communication interface4 - USB (2)
 8. Internet Protocol, OSI reference model, packet communication, configuration of computer network
 9. The first layer communication, The second layer communication
10. The third layer communication 1 （outline, IP address, Subnet）
11. The third layer communication 2 （Details of the third layer communication, ARP, router, routing）
12. Routing protocol
13. The 4th layer communication （TCP）
14. The 4th layer communication （UDP), IPv6
15. Application protocol

[Title]				[Instructor]		
Advanced Medical and Welfare Devices Engineering				Hidetsugu Terada		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ509	2	Mechatronics		1st Semester	Mon.／II	

[Outline and purpose]

Medical and welfare equipment must be not only equipment from the viewpoint of engineering but also equipment that fully secures biological safety. Therefore, understanding of laws such as complicated approval / certification / business permission, risk management, electric safety / electromagnetic compatibility, complex understanding of the market are essential. In this lecture, we learn about various matters necessary in the process of newly developing medical and welfare equipment based on the needs of the medical field and the welfare site.

[Objectives]

(1) It can understand the ensuring safety of medical and welfare equipment.
(2) Clinical tests can be planned by themselves and application documents to be submitted to the Ethics committee can be prepared.
(3) It can understand medical device certification and welfare equipment authentication procedure.

[Requirements]

The fundamental knowledge of calculus, algebra, kinematics, machine elements design and mechanics of materials are needed. Also, you need English to read the reference papers.

[Evaluation]

Reports :50%
Test: 50%

[Textbooks]

We will distribute reference papers if necessary.

[References]

None

[Schedule]

Because the plan of the medical department has not been decided, the detailed schedule is undecided. Considering the medical service in our hospital, the lecture hour for several times will be from 18:00 to 21:00 on Tuesday.
The first lecture will be started at April 13th, II period. Please check announcement in CNS.

[Title]				[Instructor]		
Mechatronics Special Lecture I						
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ601	1	Mechatronics		Intensive	／	Japanese

[Outline and purpose]

The lecture indicates the state of the art of mechatronics.

[Objectives]

To acquire the interdisciplinary knowledge on mechatronics engineering based on the knowledge of mechanics, electronics and computer science.

[Requirements]

Basic knowledge of mechatronics for undergraduate level.

[Evaluation]

Presentation 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Mechatronics Special Lecture II						
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ602	1	Mechatronics		Intensive	／	Japanese

[Outline and purpose]

The lecture indicates the state of the art of mechatronics.

[Objectives]

To acquire the interdisciplinary knowledge on mechatronics engineering based on the knowledge of mechanics, electronics and computer science.

[Requirements]

Basic knowledge of mechatronics for undergraduate level.

[Evaluation]

Presentation 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Seminar in Mechatronics Engineering IA				all academic supervisors		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ603	1	Mechatronics		1st Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the seminar.

[Objectives]

To direct one's study through the knowledge from this seminar.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation : 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Seminar in Mechatronics Engineering IB				all academic supervisors		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ604	1	Mechatronics		2nd Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the seminar.

[Objectives]

To direct one's study through the knowledge from this seminar.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation：100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Seminar in Mechatronics Engineering IIA				all academic supervisors		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ605	1	Mechatronics		1st Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field in addition to the Seminar I. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the seminar.

[Objectives]

To direct one's study through the knowledge from this seminar.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation : 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Seminar in Mechatronics Engineering IIB				all academic supervisors		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ606	1	Mechatronics		2nd Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field in addition to the Seminar I. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the seminar.

[Objectives]

To direct one's study through the knowledge from this seminar.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation : 100%

[Textbooks]

[References]

[Schedule]

[Title]	[Instructor]
Research Work in Mechatronics Engineering IA	all academic supervisors

[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ607	2	Mechatronics	1st Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the research.

[Objectives]

To direct one's study through the knowledge from this research.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation : 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Research Work in Mechatronics Engineering IB				all academic supervisors		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ608	2	Mechatronics		2nd Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the research.

[Objectives]

To direct one's study through the knowledge from this research.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation : 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Research Work in Mechatronics Engineering IIA				all academic supervisors		
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ609	2	Mechatronics		1st Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field in addition to the Research I. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the research.

[Objectives]

To direct one's study through the knowledge from this research.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation : 100%

[Textbooks]

[References]

[Schedule]

[Title]		[Instructor]	
Research Work in Mechatronics Engineering IIB		all academic supervisors	

[Code]	[Credits]	[Program]	[Semester]	[Hours]	[Language of instruction]
GTJ610	2	Mechatronics	2nd Semester		English／Japanese

[Outline and purpose]

It is necessary to review the related literatures, to consider the theme of research, including foreign journals of the related field in addition to the Research I. This program provides information on approaching those literatures. Other than that, the way of communication and collaboration on research group is also studied through the research.

[Objectives]

To direct one's study through the knowledge from this research.

[Requirements]

General knowledge of engineering relating research at undergraduate course.

[Evaluation]

Integrated evaluation : 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Mechatronics Special Lecture III						
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ611	1	Mechatronics		Intensive	／	Japanese

[Outline and purpose]

The lecture indicates the state of the art of mechatronics.

[Objectives]

To acquire the interdisciplinary knowledge on mechatronics engineering based on the knowledge of mechanics, electronics and computer science.

[Requirements]

Basic knowledge of mechatronics for undergraduate level.

[Evaluation]

Presentation 100%

[Textbooks]

[References]

[Schedule]

[Title]				[Instructor]		
Mechatronics Special Lecture IV						
[Code]	[Credits]	[Program]		[Semester]	[Hours]	[Language of instruction]
GTJ612	1	Mechatronics		Intensive	／	Japanese

[Outline and purpose]

The lecture indicates the state of the art of mechatronics.

[Objectives]

To acquire the interdisciplinary knowledge on mechatronics engineering based on the knowledge of mechanics, electronics and computer science.

[Requirements]

Basic knowledge of mechatronics for undergraduate level.

[Evaluation]

Presentation 100%

[Textbooks]

[References]

[Schedule]