		[Title]	[Instructor]				
	Advan	ced Thermo-Physical Engineering	Tetsı Toriyam	uaki Takeda a/Shumpei I	/ Koji Funatani		
[Code]	[Credits]	[Program]	[Semester] [Hours] [Langua instruc				
PTV701	2	System Integration Engineering Course	2nd Semester	Wed./II	Japanese		
[Outline and purpose]							
It is a techn storage, and in the pract	It is a technologically important problem to increase the conversion efficiency of the thermal energy. Transport, storage, and conversion of the thermal energy are explained. In addition, effective utilization of thermal energy in the practical system is described.						
[Objectives]							
Generation The utilizat	, conversion tion efficier	n, and use of the thermal energy can be understood acy of the thermal energy can be evaluated.					
[Requireme	ents]						
Thermodyn	amics, Hyd	lrodynamics, Thermal engineering, Fluid engineeri	ng, Numerica	l analysis			
[Evaluation	1]						
Report & ex Presentatio	xamination on skill:40	: 60% %					
[Textbooks]							
Not specify							
[References	3]						
Not specify Distribute i	research pa	pers, if necessary					
[Schedule]							
 1 Introduction 2-4 Production, storage, and transport of thermal energy 5 Evaluation of thermal energy system by theoretical approach and numerical analysis 6-8 Heat transport by thermal conduction, forced convection, natural convection, and thermal radiation 9-10 Conversion system of thermal energy and thermal efficiency 11-12 Renewable energy systems, such as solar thermal energy, wind energy, hydraulic energy, geothermal energy, etc. 13 Nuclear energy system and nuclear safety 14 Flow visualization techniques 15 Heat utilization systems such as thermoelectric conversion element, ground source heat pump system, etc. 							

[Title]			[Instructor]					
	Tu	rbulent Transport Engineering	Hir Yosł	Hiroyuki Tsunoda / Yoshinobu Yamamoto				
[Code]	[Credits]	[Program]	[Semester] [Hours] [Language instructio					
PTV702	2	System Integration Engineering Course	2nd Semester	Fri./I	Japanese			
[Outline an	[Outline and purpose]							
Many of pr numbers. T flow. In ord difference b and the stat described an as being mo can be app boundary-la students wi [Objectives] In the desig related with moreover w students are 1. to under 2. to under 3. to discu	[Outline and purpose]Many of practical flows appearing in the field of mechanical engineering are turbulent of high Reynolds numbers. Turbulent flow is known to have remarkably effective transport ability in comparison with laminar flow. In order to understand physical features of the turbulent flow, students will study the fluid-mechanical difference between laminar and turbulent flows, flow instability problems related with the turbulence transition and the statistical properties of turbulence. Then, the fundamental ideas how the turbulent flow is statistically described are discussed in the case of isotropic turbulence for which theoretical approaches have been completed as being most elementary and simplest turbulent flow. These statistical techniques for the isotropic turbulence can be applied to the analysis of more practical anisotropic turbulent shear flows such as pipe flow, boundary-layer flow or free shear flows. By investigating the momentum and thermal transport equations, students will learn experimental and numerical analysis methods for these flows.[Objectives]In the design and the development of various machines or apparatuses, there are many practical problems related with fluid engineering. This course aims to educate engineers who can manage these problems and moreover who have an ability to apply their knowledge to the creation of new technology. For this objective, students are expected to complete the following goals:1. to understand the fundamental idea of turbulence 2. to understand the fundamental idea of turbulence							
[Requireme	nts]	<i>(</i> 1 · 1 · 1 1 · 1 1 · 1 · 	1 1	. 1				
Overall kno fundamenta	wledge on al and appl	ied knowledge on calculus, fundamental knowledge	e under-gradu e on vector cal	ate and grac culus	uate courses,			
[Evaluation	.]							
homework : presentation	80% n:20%							
[Textbooks]								
References								
 Davidsor 日野幹雄 Tenneke Po 	n, P.A.: Turb 註: 流体力 es, H. and l ne SB:T	ulence: An Introduction for Scientists and Engineers, Ox 学,朝倉書店, ISBN 4254200668 (in Japanese). Lumley, J.L. : A First Course in Turbulence, The MI Lurbulent Flows, Cambridge University Press, 2000	ford Univ. press T press, 1972 ISBN 05215	s, 2004, ISBN , ISBN 0262 98869	0198529481 200198.			
[Schedule]	<u>p-,</u>		,					
1. Introduction 2. Laminar and turbulent flows #1 3. Laminar and turbulent flows #2 4. Flux and turbulent transport 5. Isotropic turbulence #1 6. Isotropic turbulence #2 7. Reynolds equations 8. Turbulent flows in pipe 10. Boundary layer 11. Free shear flows 12. Several turbulence models and DNS 13. Measurement techniques of turbulent flows #1 14. Measurement techniques of turbulent flows #2 15. Summary								

		[Title]	[Instructor]			
	Ad	vanced Materials Engineering	Yoshihiro Nakayama / Yasumi Ito/ Yoshiyuki Kagiyama			
[Code]	[Credits]	[Program]	[Semester] [Hours] [Languaginstruct			
PTV703	2	System Integration Engineering Course	1st Semester	Fri./I	Japanese	
[Outline an The aim of materials, "materials materials a materials, v structures. [Objectives] 1. To unde 2. To unde 3. To unde	[Outline and purpose] The aim of this module is to introduce students to the advanced materials researches, which include metallic materials, biocompatible materials, and biomaterials, and to provide students with in-depth knowledge of "materials science". In the first half of the term, we will focused on structural characteristics of metallic materials and the application examples. In the latter half of the term, we will focused on biocompatible materials, which have been developed in medical engineering, and failure accident investigation of machines and structures. [Objectives] 1. To understand the advanced applications of metallic materials and biocompatible materials 2. To understand the safety evaluation of metallic materials and biocompatible materials 3. To understand the failure accident investigating method of machines and structure					
Materials s Basic stren	cience and gth of mate	engineering erials				
[Evaluation	n]					
Homework:	50%	0/				
Fresentatio	m work+ 50	20				
[Textbooks]						
N. A.						
[References	s]					
伊藤安海, ISBN:978-4	鍵山善之, 1-904419-69	イラスト医工学 -バイオメカニクスから医療 }-4	機器・科学技	捜査まで-,	アドスリー,	
[Schedule]						
 Orienta Structu Applica Applica Applica Besearce Metallie Biocom Artificia Finite e Advance Biomece Mechan Materia 	tion, Meta re and prop tion examp tion examp ch trend of c materials patible mar al joint imp element ana ed research hanical ma nical proper al and dyna	llic materials for infrastructure materials perties of metallic materials ble 1 of metallic materials ble 2 of metallic materials metallic materials in medical applications terials blants alysis of artificial joint implants hes in medical engineering terial and biomechanics rties of biological tissue mics in medical engineering				
14. Failure 15. Psychia	4. Failure accident investigating method of machines and structures from mechanical property5. Psychiatry theoretical structure based on strength of materials and summary					

[Title]				[Instructor]			
	Adv	vanced Color Image Technology	Shinji Kotani				
[Code]	[Credits]	[Program]	[Semester] [Hours] [Language instruction				
PTV707	2	System Integration Engineering Course	1st Semester	Wed.∕IV	Japanese		
[Outline an	[Outline and purpose]						
Starting with how our eyes recognize color, we will explain important issues such as color space, measurement of color and their practical applications for engineering design.							
[Objectives]							
 Being a Unders Instrum translat Get use 	ble to expla tand severa nent of mea te Analog fi ed to tools fo	ain how our eyes recognize colors. al color systems and difference between them. suring color gures to digital ones or handling color and simulate color images on PC.					
Requireme	ents						
Fundament	al knowled	ge about spectra of light and some mathematical sl	kill for vector	space			
[Evaluation	ı]						
final exami	nation: 50%	0					
presentatio	n: 50%						
[Textbooks]							
Not Specifi	ed.						
[References]						
Not Specific	ed.						
[Schedule]							

[Title]			[Instructor]					
	Advan	ced Wave Application Engineering	Takaaki Ishii / Toshiya Kitamura					
[Code]	[Credits]	[Program]	[Semester] [Hours] [Languaginstruct					
PTV708	2	System Integration Engineering Course	2nd Semester	Wed./IV	Japanese			
[Outline an	[Outline and purpose]							
Wave is basic physical phenomenon. A lot of applications are widely used in our society and understanding wave technology is very important. Deep and thorough understanding of the fundamentals and applications of wave is greatly expected in this course.								
[Objectives]								
1. to unders	stand the fu	andamentals and applications of the wave						
[Requireme	ents]							
Fundament electrics an	al knowled d electroni	lge of the acoustics, physics, mathematics, chemist c engineering, etc.	try, materials,	mechanical	engineering,			
Evaluation	1							
Report : 80 ^o Attitude : 2	% 0%							
[Textbooks]								
None								
[References	5]							
 山田伸志 Kenji Uc Kenji Uc Kenji Uc 	1. 山田伸志, 黒崎茂, 小坂敏文, 松村志真秀, 吉村靖夫, 渡辺敏夫 : 振動工学入門, パワー社 2001 年 (in Japanese) 2. Kenji Uchino : Ferroelectric devices, Marcel Dekker (2000) 3. Kenji Uchino, Jayne Giniewicz : Micromechatronics, Marcel Dekker (2003) 4. 城戸健一 : ディジタルフーリエ解析(II), コロナ社 2007 年 (in Japanese)							
[Schedule]								
1. Fundame 2. Fundame 3. Fundame	entals and a entals and a entals and	applications of ferroelectrics applications of ultrasonics applications of the acoustics						
4. Measure	4. Measurements and applications of the analysis technology							

		[Title]	[Instructor]				
		Applied Robotics	No Hidetsugu Z	buyuki Furu Ferada/Kazu	ya / yoshi Ishida		
[Code]	[Credits]	[Program]	[Semester] [Hours] [Language instruction				
PTV709	2	System Integration Engineering Course	2nd Semester	Mon./II	Japanese		
[Outline an	[Outline and purpose]						
Learning about the mechanism and control of robots by the latest robotics papers, then the design method of robots will be discussed.							
[Objectives]							
(1) to under(2) to under(3) to under	stand the s stand profestand the l	structure of robot mechanism and be able to design essional item of robot control technology. atest trends in robotics research	various robot	s.			
[Requireme	nts]						
Grounding knowledge	in calculus of robotics.	, algebra, knowledge of kinematics, dynamics, mec Also and in some cases, the materials are written i	hanical desigi n English.	n and mater	ial, assuming		
[Evaluation	l]						
1. Small tes 2. Routine t	st and Pres cest and Re	entation 80% port 20%					
Touthooka							
Textbook is	not used. I	Materials will be provided.					
[References]						
 Control SIGNAI 現代制御 	system des LS AND LII 『理論入門,	ign, McGRAW-HILL, ISBN:0486442780 NEAR SYSTEMS,Jhon Wiley & Sons,ISBN:047183 コロナ社, ISBN:4339031615 (In Japanese)	8217				
4. Mark	E. Roshein	n, Robot Evolution -The Development of Auth	robotics-, Jol	hn Wiley &	Sons, Inc.,		
[Schedule])26220						
Do a lecture on the content of the following from the perspective of designing a robot. 1. Mechanism of the robot (1-5 times) To discuss about the forward kinematics and the inverse kinematics solution and the derivation techniques of three-dimensional mechanism with the singular points analysis of serial and parallel robots, focusing on the differences in particular. 2. Robot control (6 to 10)							
To discuss about the control algorithm of Point to Point and Continuous path control, explaining about the practical path control and interpolation method. Communication systems and servo mechanism with the examples be explained. 3. Intelligent Robots (11 times to 15 times) To discuss how intelligent robot will be constructed using smart sensor system, and be explained a variety of image recognition techniques and algorithms in robot.							

		[Title]	[Instructor]			
Advanced Human-Machine Interface			Tomoo Munehisa / Yoshimi Suzuki / Hiromitsu Nishizaki			
[Code]	[Credits]	[Program]	[Semester] [Hours] [Language instructio			
PTV710	2	System Integration Engineering Course	2nd Semester	Fri./IV	Japanese	
[Outline and purpose] In this course, the lecturers instruct on some information technologies which help a human-machine (robot) communications. For example, the lecturers explain on speech processing, natural language (text) processing, and image processing. In addition, they also explain artificial intelligence algorithms such as deep learning and genetic algorithm. [Objectives] (1) The students can understand artificial intelligence (AI) algorithms (such as deep learning and genetic algorithm) and also approximate Algorithm (such as deep learning and genetic algorithm).						
(2) The stud	dents can n	nake some applications on a robot or a computer us	ing these AI-r	elated algor	ithms.	
[Requireme Programmi	ents] ng skills fo	r C and Python languages are required.				
[Evaluation	1]					
Reports: 10	0%					
[Textbooks]						
Nothing						
[References Kohji Maki (牧野浩二ほ	5] no et al., "T か, 算数&	Deep Learning with arithmetic & Raspberry Pi," CC ラズパイから始めるディープラーニング,CQ 出版社) publishing C z, 2018)	o. Ltd., 2018	3	
[Schedule]						
 Introduct Outline of Outline of Outline of Deep lease Deep lease	tion (outlin of speech pr of natural la rning basic rning basic rning advar rning advar arning advar algorithm algorithm ion of recer ion of recer	e of AI technologies) pocessing anguage processing edition No.1: neural network edition No.2: convolutional neural network edition No.3: recurrent neural network nced No.1: application for speech processing nced No.2: application for temporal sequence data nced No.3: application for text processing anced No.4: application for text processing basic edition advanced edition nt researches on AI No.1 nt researches on AI No.2 at researches on AI No.3				

		[Title]	[Instructor]			
		Advanced Robot Design	Shinji Kotani / Miyoshi Okamura /Shinichiro Hira / Tsutomu Tanzawa			
[Code]	[Credits]	[Program]	[Semester] [Hours] [Languag instruct			
PTV711	2	System Integration Engineering Course	1nd Semester	Fri./III	Japanese	
[Outline and purpose] In order to design a robot, it is indispensable to integrate engineering systems of mechanical technology, electronic technology, information communication technology, control technology. The purpose of this class is to cultivate indispensable essentials for robot design.						
[Objectives • to explain • to decide • to propos] n the purpo and explai e and expla	ese, background and meaning of the robot to be desi n mechanism, actuator, electronic, information com ain evaluation method of the designed robot	gned munication, a	and control s	ystem	
[Requireme Basic know measureme	ents] vledge of n ent enginee	nathematics, physical, mechanical elements, matering	erial dynamic	s, electronic	e circuits and	
[Evaluation	1]					
assignment	25%、pres	sentation 25%、discussion 50%				
[Textbooks]						
specify in t	he class					
[References	8]					
specify in t	he class					
[Schedule]						
 Introduc Requests Ethics and Autonom Symphony 	 Introduction of conventional Robot Design Requests to Robots under various environments Ethics and Philosophy in Robot Design Autonomous Robot 					
 6. Summary (presentation & discussion) 7. Materials (1)_Structural Materials (guide for choice, strength Tests, processing methods) 8. Materials (2)_Functional Materials (purpose of use, application cases) 9. Structure (mechanism_actuator) 						
10. Summa 11. Sensing	10. Summary (presentation & discussion) 11. Sensing					
13. Electron 10. Summa 15. Present	 Software , Network Electronic Circuit , Safety Function Summary (presentation & discussion) Presentation & Discussion 					

		[Title]	[Instructor]			
		Optical Engineering	Masayuk Shin	ti Morisawa 11zu / Lianhu	/Tsuyoshi 1a Jin	
[Code]	[Credits]	[Program]	[Semester] [Hours] [Language instruction			
PTV712	2	System Integration Engineering Course	1nd Semester	Mon. / IV	Japanese	
[Outline and purpose]SemesterNumerous contemporary sensing techniques using optical methodology and image processing have been developed and applied to various products. Taking into consideration the rapid developments of prospective precision instruments and measurement instruments, acquisition of basic technology is extremely valuable. This course covers following optical sensing techniques and its applications.1. Basic of polarization instrumentation and its application to nano-technology (Responsible: Prof. Jin)2. Instrumentation with optical fiber and its application (Responsible: Prof. Morisawa)3. Imaging processing and its application (Responsible: Prof. Shimizu)This lecture aims to help the student cultivate fundamental ability to utilize above techniques to various engineering systems.[Objectives](A) Understand polarization phenomenon and polarization measurements.(B) Explain spectroscopic polarization instrumentation and its application.(C) Understand the operation principles of optical fiber sensor for measurement of physical quantities such as temperature, pressure etc.(D) Explain the operation principles of chemical optical fiber sensor for detection of various gases.(E) Understand the geometry optics of the camera and illumination system.(F) Explain the image processing method and its application.(F) Explain the image processing method and its application.(Requirements]A grounding in algebra, analytics, statistics, and physics						
Textbooks	10070					
	1					
[References						
[Schedule] 1. Reflection and polarized light 2. Polarization measurement system 3. Spectroscopic ellipsometry 4. Spectroscopic ellipsometry and nanotechnology 5. Summary (Part 1) 6. Fundamentals of optical fiber sensors 7. The optical fiber sensor for measurement of physical quantities 8. Fundamentals of chemical optical fiber sensor 9. Application of chemical optical fiber sensor 10. Summary (Part 2) 11. Geometric camera model and geometric camera calibration 12. Radiometry, lightning and image processing 13. Visual inspections 14. Image processing and machine learnings 15. Summary (Part 3)						